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ON THE MATRIX EQUATION FOR A SPIN 2 PARTICLE IN PSEUDO-RIEMANNIAN SPACE-TIME

After the study by Pauli and Fierz [1, 2], the theory of massive and massless fields with spin 2 has always attracted much attention [3-13]. Most of the studies were performed in the framework of 2-nd order differential equations. It is known that many specific difficulties may be avoided if from the very beginning we start with 1-st order systems. Apparently, the first systematic study of the theory of spin 2 fields within the first order formalism was done by F. I. Fedorov [4]. It turns out that this description requires a field function with 3 independent components. This theory was re-discovered and improved by Regee [5]. In the present paper we develop the theory of the spin 2 field, in both massive and massless variants, starting from the matrix equation in Minkowski space-time and extending it to the generally covariant theory within the Tetrode-Weyl-Fock-Ivanenko tetrad method.

We start with the known system of the first order equations for a massive spin 2 particle:

$$\partial^{a}\Phi_{a} = m\Phi, \quad \frac{1}{2}\partial_{a}\Phi_{a} - \frac{1}{2}\partial_{b}\Phi_{a} = m\Phi_{a},$$

$$\frac{1}{2}\left(\partial^{k}\Phi_{[ka]b} + \partial^{k}\Phi_{[kb]a} - \frac{1}{2}g_{ab}\partial^{k}\Phi_{[kn]}^{n}\right) + \left(\partial_{a}\Phi_{b} + \partial_{b}\Phi_{a} - \frac{1}{2}g_{ab}\partial^{k}\Phi_{k}\right) = m\Phi_{(ab)},$$

$$\partial_{a}\Phi_{(bc)} - \partial_{b}\Phi_{(ac)} + \frac{1}{3}\left(g_{bc}\partial^{k}\Phi_{(ak)} - g_{ac}\partial^{k}\Phi_{(bk)}\right) = m\Phi_{[ab]c}, \quad (1)$$

where the field variables are scalar, vector, symmetric 2-rank tensor, and 3-rank skew-symmetric in two first indices tensor, m = iM. By excluding the vector and the 3-rank tensor, we obtain the 2-nd order equations with respect to the scalar and symmetric tensor:

$$\Phi = 0, \quad (+M^2)\Phi_{(ab)} = 0, \quad \Phi_{(ab)} = \Phi_{(ba)}, \quad \Phi^a_a = 0, \quad \partial^k \Phi_{(ka)} = 0.$$
(2)

In massless case, the first order system reads

$$\partial^{a}\Phi_{a} = 0, \frac{1}{2}\underline{\partial}_{a}\Phi_{a} - \frac{1}{2}\partial^{b}\Phi_{a} = \Phi_{a},$$

$$\frac{1}{2}\left[\partial^{k}\Phi_{[ka]b} + \partial^{k}\Phi_{[kb]a} - \frac{1}{2}g_{ab}\partial^{k}\Phi_{[kn]}^{n}\right] + \left[\partial_{a}\Phi_{b} + \partial_{b}\Phi_{a} - \frac{1}{2}g_{ab}\partial^{k}\Phi_{k}\right] = 0,$$

$$\partial_{a}\Phi_{(bc)} - \partial_{b}\Phi_{(ac)} + \frac{1}{2}\left[g_{bc}\partial^{k}\Phi_{(ak)} - g_{ac}\partial^{k}\Phi_{(bk)}\right] = \Phi_{[ab]c}.$$
(3)

From (3) we derive the 2-nd order equations for the massless field:

$$\frac{1}{2} \Phi - \frac{1}{2} \partial^k \partial^l \Phi = 0,$$

$$(\partial_a \partial_b + \frac{1}{2} g_{ab}) \Phi - \frac{1}{4} g_{ab} \Phi^c + \Phi = -\partial_a \partial^l \Phi = 0.$$
(4)

Massless equations have a class of gauge solutions:

$$\Phi = \partial^l L, \quad \Phi_{(ab)} = \partial_a L_b + \partial_b L_a - \frac{1}{2} g_{ab} \partial^l L, \quad (5)$$

where $L_l(x)$ stands for an arbitrary 4-vector. These special states do not contribute to physically observable quantities, like the energy-momentum tensor. The concomitant gauge components are as follows:

$$\Phi_{a} = \frac{1}{3} \frac{\partial}{\partial a} \frac{\partial^{l} L}{\partial a} - \frac{1}{3} \frac{L}{a}, \Phi_{[ab]c} = \frac{\partial}{c} (\frac{\partial}{\partial a} \frac{L}{b} - \frac{\partial}{\partial b} \frac{L}{a}) - \frac{g_{cb} \partial_{a} - g_{ca} \partial_{b}}{3} \frac{\partial^{l} L}{\partial a} + \frac{g_{cb} L_{a} - g_{ca} L_{b}}{3}.$$
 (6)

The system (1) can be re-written in equivalent block form

$$\partial_{a} (G^{a})_{(0)}^{k} \Phi_{k} = m \Phi_{(0)}, \quad \partial_{a} \left\{ \frac{1}{2} (\Delta^{a})_{k}^{(0)} \Phi_{(0)} - \frac{1}{3} (K^{a})_{k}^{(mn)} \Phi_{mn} \right\} = m \Phi_{k}, \\ \partial_{a} \left\{ \frac{1}{2} (B^{a})_{(cd)}^{[mn]l} \Phi_{mnl} + (\Lambda^{a})_{(dc)}^{k} \Phi_{k} \right\} = m \Phi_{dc}, \partial_{a} \left\{ (F^{a})_{[kb]c}^{(mn)} \Phi_{mn} \right\} = m \Phi_{kbc}, \quad (7)$$

The corresponding matrix equation

$$\left(\Gamma^{a}\frac{\partial}{\partial x^{a}}-m\right)\Psi(x)=0,\quad\Psi=\left\{H;H_{1};H_{2};H_{3}\right\}$$
(8)

is extended to the Riemannian space-time in accordance with the tetrad method. In a space-time with given metric, we fix a tetrad:

$$dS^{2} = g_{\alpha\beta}(x)dx^{\alpha}dx^{\beta}, \quad g_{\alpha\beta}(x) \to e_{(a)\alpha}(x), \ g_{\alpha\beta}(x) = \eta^{ab}e_{(a)\alpha}(x)e_{(b)\beta}(x), \quad (9)$$

and then the generalized form gets written as follows

$$\begin{bmatrix} \Gamma^{\alpha}(x) \begin{pmatrix} \partial \\ \partial x^{\alpha} \end{pmatrix} + \Sigma_{\alpha}(x) \\ \partial x^{\alpha} \end{pmatrix} - m \end{bmatrix} \Psi(x) = 0, \qquad (10)$$

where the local matrices $\Gamma^{\alpha}(x)$ are determined with the use of the tetrad

$$\Gamma^{\alpha}(x) = e^{\alpha}_{(a)}(x)\Gamma^{a} = \begin{pmatrix} 0 & G^{\alpha}(x) & 0 & 0 \\ \frac{1}{2}\Delta^{\alpha}(x) & 0 & -\frac{1}{3}K^{\alpha}(x) & 0 \\ 0 & \Lambda^{\alpha}(x) & 0 & \frac{1}{2}B^{\alpha}(x) \\ 0 & 0 & F^{\alpha}(x) & 0 \end{pmatrix},$$
(11)

and connection $\Sigma_{\alpha}(x)$ is defined by relations

$$\Sigma_{\alpha}(x) = J^{ab} e^{\beta}_{(a)}(x) e_{(b)\beta;\alpha}(x) = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & (\Sigma_{1})_{\alpha} & 0 & 0 \\ 0 & 0 & (\Sigma_{2})_{\alpha} & 0 \\ 0 & 0 & 0 & (\Sigma_{3})_{\alpha} \end{bmatrix},$$
(12)

where $\sum_{i} (x) = J_{i}^{ab} e_{(a)}^{\beta}(x) e_{(b)\beta;\alpha}(x)$, i = 1, 2, 3; and $J_{1}^{ab}, J_{2}^{ab}, J_{3}^{ab}$ stand for the generators for the tensors $\Phi_k, \Phi_{(mn)}, \Phi_{[mn]l}$. The equation (10) can be presented by using the Ricci rotation coefficients

$$\begin{bmatrix} \Gamma^{c} \Big|^{\ell} e^{\alpha}(x) & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ \int g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g^{abc} & \frac{\partial}{\partial x^{\alpha}} + \frac{1}{2} J^{ab} \gamma \\ g$$

In block form, eq. (13) reads

$$G^{\alpha}(x)\left[\partial_{\alpha} + (\Sigma_{1})\right]H_{1} = mH, \quad \frac{1}{2}\Delta^{\alpha}(x)\partial_{\alpha}H - \frac{1}{3}K^{\alpha}(x)\left[\partial_{\alpha} + (\Sigma_{2})\right]H_{2} = mH,$$

$$\Lambda^{\alpha}(x)\left[\partial_{\alpha} + (\Sigma_{1})\right]H_{1} + \frac{1}{2}\left[\partial_{\alpha} + (\Sigma_{3})\right]H_{3} = mH, \quad F^{\alpha}(x)\left[\partial_{\alpha} + (\Sigma_{2})\right]H_{2} = mH,$$

In the massless case, the system slightly changes:

$$G^{\alpha}(x)\left[\partial_{\alpha} + (\Sigma_{1})\right]H_{1} = 0, \quad \frac{1}{2}\Delta^{\alpha}(x)\partial_{\alpha}H - \frac{1}{3}K^{\alpha}(x)\left[\partial_{\alpha} + (\Sigma_{1})\right]H_{2} = H_{1},$$

$$\Lambda^{\alpha}(x)\left[\partial_{\alpha} + (\Sigma_{1})\right]H_{1} + \frac{1}{2}\left[\partial_{\alpha} + (\Sigma_{3})\right]H_{3} = 0, \quad F^{\alpha}(x)\left[\partial_{\alpha} + (\Sigma_{2})\right]H_{2} = H_{3},$$

but its physical content is completely different. In particular, let us detail tetrad representation for the gauge solutions:

$$\Phi = \nabla_{\alpha} L^{\alpha}(x) \implies \Phi = e^{(c)\alpha} \partial_{\alpha} L_{(c)} + e^{\alpha}_{(c);\alpha} L^{(c)},$$

$$\Phi_{(\alpha\beta)} = \nabla_{\alpha} L_{\beta} + \nabla_{\beta} L_{\alpha} - \frac{1}{2} g_{\alpha\beta}(x) \nabla_{\beta} \Lambda^{\rho} \implies$$

$$\Phi_{(ab)} = -\left(\gamma_{[ca]b} + \gamma_{[cb]a}\right) L^{(c)} + e^{\alpha}_{(a)} \partial_{\alpha} \Lambda_{(b)} + e^{\alpha}_{(b)} \partial_{\alpha} \Lambda_{(a)} - \frac{1}{2} g_{ab} \Phi. \quad (14)$$

The concomitant gauge components are determined by the formulas

$$H_{1} = \frac{1}{2} \Delta^{\alpha}(x) \partial_{\alpha} H - \frac{1}{3} K^{\alpha}(x) [\partial_{\alpha} + (\Sigma_{2\alpha})] H_{2}, \quad H_{3} = F^{\alpha}(x) [\partial_{\alpha} + (\Sigma_{2\alpha})] H_{2}.$$
(15)

The covariant equation is symmetric under the local Lorentz group, in accordance with the following relations

$$\Psi'(x) = S(x)\Psi(x), \quad S(x)\Gamma^{\alpha}(x)S^{-1}(x) = \Gamma^{\prime\alpha}(x),$$

$$S(x)\Sigma_{\alpha}(x)S^{-1}(x) + S(x) \xrightarrow{\partial} S^{-1}(x) = \Sigma^{\prime},$$

$$\partial x^{\alpha} \qquad \alpha$$
(16)

where the prime indicates that quantities are determined with the use of the primed tetrad related to initial one by the local Lorentz transformation $e_{(a')}^{\sigma}(x) = L_a^{b}(x) e_{(b)}^{\sigma}(x)$. With respect to the coordinate transformation, the field function Ψ behaves as a scalar, $x^{\alpha} \rightarrow x^{\prime \alpha}$, $\Psi(x) = \Psi'(x')$.

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