A. Ivashkevich, A. Buryy, E. Ovsiyuk, V. Balan, V. Kisel, V. Red'kov<br>B. I. Stepanov Institute of Physics,<br>National Academy of Sciences of Belarus, Minsk, Belarus

## ON THE MATRIX EQUATION FOR A SPIN 2 PARTICLE IN PSEUDO-RIEMANNIAN SPACE-TIME

After the study by Pauli and Fierz [1, 2], the theory of massive and massless fields with spin 2 has always attracted much attention [3-13]. Most of the studies were performed in the framework of 2-nd order differential equations. It is known that many specific difficulties may be avoided if from the very beginning we start with 1 -st order systems. Apparently, the first systematic study of the theory of spin 2 fields within the first order formalism was done by F. I. Fedorov [4]. It turns out that this description requires a field function with 3 independent components. This theory was re-discovered and improved by Regee [5]. In the present paper we develop the theory of the spin 2 field, in both massive and massless variants, starting from the matrix equation in Minkowski space-time and extending it to the generally covariant theory within the Tetrode-Weyl-Fock-Ivanenko tetrad method.

We start with the known system of the first order equations for a massive spin 2 particle:

$$
\begin{align*}
& \partial^{a} \Phi_{a}=m \Phi, \quad \frac{1}{2}_{2_{a}} \Phi-{ }^{1} \partial^{b} \Phi_{(a b)}=m \Phi, \\
& \frac{1}{2}\left(\partial^{k} \Phi_{[k a] b}+\partial^{k} \Phi_{[k b] a}-\frac{1}{2} g_{a b} \partial^{k} \Phi_{[k n]}{ }^{n}\right)+\left(\begin{array}{c}
3 \\
\left.\partial_{a} \Phi_{b}+\partial_{b} \Phi_{a}-\frac{1}{2} g_{a b} \partial_{k} \Phi_{k}\right)=m \Phi_{(a b)}, ~, ~, ~, ~
\end{array}\right. \tag{1}
\end{align*}
$$

where the field variables are scalar, vector, symmetric 2-rank tensor, and 3 -rank skew-symmetric in two first indices tensor, $m=\mathrm{i} M$. By excluding the vector and the 3-rank tensor, we obtain the 2-nd order equations with respect to the scalar and symmetric tensor:

$$
\begin{equation*}
\Phi=0, \quad\left('^{\prime}+M^{2}\right) \Phi_{(a b)}=0, \quad \Phi_{(a b)}=\Phi_{(b a)}, \quad \Phi_{a}^{a}=0, \quad \partial^{k} \Phi_{(k a)}=0 . \tag{2}
\end{equation*}
$$

In massless case, the first order system reads

$$
\begin{align*}
& \partial^{a} \Phi_{a}=0,{\underset{2}{2}}_{a}^{1} \Phi^{\frac{\partial}{2}}{ }^{1} \partial^{b} \Phi_{(a b)}=\Phi_{a}, \\
& \frac{1}{2}\left(\partial^{k} \Phi_{[k a] b}+\partial^{k} \Phi_{[k b] a}-\frac{1}{2} g_{a b} \partial^{k} \Phi_{[k n]}^{n}\right)^{3}+\left(\partial_{a} \Phi_{b}+\partial_{b} \Phi_{a}-\frac{1}{2} g_{a b} \partial_{k} \Phi_{k}\right)=0, \\
& \left.\partial \underset{a}{\Phi_{(b c)}}-\partial_{b}^{\Phi_{(a c)}}+\underset{3^{\prime}}{1} g_{b c} \partial^{k} \Phi_{(a k)}-g_{a c} \partial^{k} \Phi_{(b k)}\right)=\Phi_{[a b] c} . \tag{3}
\end{align*}
$$

From (3) we derive the 2 -nd order equations for the massless field:

Massless equations have a class of gauge solutions:

$$
\begin{equation*}
\Phi=\partial^{l} L_{i}, \quad \Phi_{(a b)}=\partial_{a} L_{b}+\partial_{b} L_{a}-\frac{1}{2} g_{a b} \partial^{l} L, \tag{5}
\end{equation*}
$$

where $L_{l}(x)$ stands for an arbitrary 4 -vector. These special states do not contribute to physically observable quantities, like the energy-momentum tensor. The concomitant gauge components are as follows:

$$
\begin{equation*}
\Phi_{a}=\frac{1}{3} \partial_{a} \partial^{l} L_{l}-\frac{1}{L_{a}} L_{a} \Phi_{[a b] c}=\partial_{c}\left(\partial{ }_{a} L_{b}-\partial_{b} L_{a}\right)-\frac{g_{c b} \partial_{a}-g_{c a} \partial_{b}}{3} \partial^{l} L_{l}+\frac{g_{c b} L_{a}-g_{c a} L_{b}}{3} . \tag{6}
\end{equation*}
$$

The system (1) can be re-written in equivalent block form

The corresponding matrix equation

$$
\begin{equation*}
\left(\Gamma^{a} \frac{\partial}{\partial x^{a}}-m\right) \Psi(x)=0, \quad \Psi=\left\{H ; H_{1} ; H_{2} ; H_{3}\right\} \tag{8}
\end{equation*}
$$

is extended to the Riemannian space-time in accordance with the tetrad method. In a space-time with given metric, we fix a tetrad:

$$
\begin{equation*}
d S^{2}=g_{\alpha \beta}(x) d x^{\alpha} d x^{\beta}, \quad g_{\alpha \beta}(x) \rightarrow e_{(a) \alpha}(x), g_{\alpha \beta}(x)=\eta^{a b} e_{(a) \alpha}(x) e_{(b)}(x), \tag{9}
\end{equation*}
$$

and then the generalized form gets written as follows

$$
\left\lceil\Gamma^{\alpha}(x)\left(\begin{array}{c}
\partial  \tag{10}\\
\partial x^{\alpha}
\end{array}+\Sigma_{\alpha}(x)\right)^{-m}\right\rceil^{-} \Psi(x)=0,
$$

where the local matrices $\Gamma^{\alpha}(x)$ are determined with the use of the tetrad

$$
\Gamma^{\alpha}(x)=e_{(a)}^{\alpha}(x) \Gamma^{a}=\left(\begin{array}{cccc}
0 & G^{\alpha}(x) & 0 & 0  \tag{11}\\
\frac{1}{2} \Delta^{\alpha}(x) & 0 & -\frac{1}{3} K^{\alpha}(x) & 0 \\
0 & \Lambda^{\alpha}(x) & 0 & \frac{1}{2} B^{\alpha}(x) \\
0 & 0 & F^{\alpha}(x) & 0
\end{array}\right),
$$

and connection $\Sigma_{\alpha}(x)$ is defined by relations

$$
\Sigma_{\alpha}(x)=J^{a b} e_{(a)}^{\beta}(x) e_{(b) \beta ; \alpha}(x)=\left[\begin{array}{cccc}
0 & 0 & 0 & 0  \tag{12}\\
0 & \left(\Sigma_{1}\right)_{\alpha} & 0 & 0 \\
0 & 0 & \left(\Sigma_{2}\right)_{\alpha} & 0 \\
0 & 0 & 0 & \left(\Sigma_{3}\right)_{\alpha}
\end{array}\right),
$$

where $\Sigma_{i}(x)=\underset{i}{J_{i}^{a b}} e_{(a)}^{\beta}(x) \underset{(b) \beta ; \alpha}{ }(x), \quad i=1,2,3$; and $\quad J_{1}^{a b}, J_{2}^{a b}, J_{3}^{a b}$ stand for the generators for the tensors $\Phi_{k}, \Phi_{(m n)}, \Phi_{[m n] l}$. The equation (10) can be presented by using the Ricci rotation coefficients

$$
\begin{equation*}
\left[\Gamma^{c^{\prime}} e^{\alpha}(x) \frac{\partial}{\partial x^{\alpha}}+\frac{1}{2}_{a b c}^{a b \gamma}{ }^{a b c}{ }^{\prime}-m\right\rceil^{(c)} \Psi(x)=0 . \tag{13}
\end{equation*}
$$

In block form, eq. (13) reads

$$
\begin{aligned}
& G^{\alpha}(x)\left[\partial_{\alpha}+\left(\Sigma_{1}\right)_{\alpha}\right] H_{1}=m H, \quad \frac{1}{2} \underline{\Delta}^{\alpha}(x) \partial{ }_{\alpha} H-{ }_{3}^{1} K^{\alpha}(x)\left[\partial \underset{\alpha}{ }+\left(\sum_{2}\right)_{\alpha}\right] H_{2}=m H \text {, } \\
& \left.\Lambda^{\alpha}(x)\left[\partial_{\alpha}+\left(\sum_{1 \alpha}\right)_{\alpha}\right] H_{1}+{\underset{2}{2}}_{1}^{[\partial} \underset{\alpha}{ }+\left(\Sigma_{3}\right)_{\alpha}\right] H_{3}=m H_{2}, \quad F^{\alpha}(x)\left[\partial_{\alpha}+\left(\sum_{2}\right)_{\alpha}\right] H_{2}=m H_{3} .
\end{aligned}
$$

In the massless case, the system slightly changes:

$$
\begin{aligned}
& \left.\Lambda^{\alpha}(x)\left[\partial_{\alpha}+\left(\sum_{1}\right)_{\alpha}\right] H_{1}+{\underset{2}{2}}_{1}^{[\partial} \underset{\alpha}{ }+\left(\Sigma_{3}\right)_{\alpha}\right] H_{3}=0, \quad F^{\alpha}(x)\left[\partial_{\alpha}+\left(\Sigma_{2}\right)_{\alpha}\right] H_{2}=H_{3},
\end{aligned}
$$

but its physical content is completely different. In particular, let us detail tetrad representation for the gauge solutions:

$$
\begin{align*}
& \Phi=\nabla_{\alpha} L^{\alpha}(x) \Rightarrow \Phi=e^{(c) \alpha} \partial_{\alpha} L_{(c)}+e_{(c) ; \alpha}^{\alpha} L^{(c)}, \\
& \Phi_{(\alpha \beta)}=\nabla_{\alpha \beta} L_{\beta}+\nabla_{\beta \alpha}^{L}-\overline{-}_{2}^{1}{ }_{\alpha \beta}^{(x) \nabla}{ }_{\rho}^{(c)} \Lambda^{(c) ; \alpha} \Rightarrow \tag{14}
\end{align*}
$$

The concomitant gauge components are determined by the formulas

The covariant equation is symmetric under the local Lorentz group, in accordance with the following relations

$$
\begin{gather*}
\Psi^{\prime}(x)=S(x) \Psi(x), \quad S(x) \Gamma^{\alpha}(x) S^{-1}(x)=\Gamma^{\prime \alpha}(x), \\
S(x) \sum_{\alpha}(x) S^{-1}(x)+S(x) \frac{\partial}{\partial x^{\alpha}} S^{-1}(x)=\Sigma^{\prime}, \tag{16}
\end{gather*}
$$

where the prime indicates that quantities are determined with the use of the primed tetrad related to initial one by the local Lorentz transformation $e_{\left(a^{\prime}\right)}^{\sigma}(x)=L_{a}{ }^{b}(x) e_{(b)}^{\sigma}(\mathrm{x})$. With respect to the coordinate transformation, the field function $\Psi$ behaves as a scalar, $x^{\alpha} \rightarrow x^{\prime \alpha}, \Psi(x)=\Psi^{\prime}\left(x^{\prime}\right)$.

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